

### Question

Derive the components of

(a) velocity and acceleration in cylindrical polar coordinates,

(b) velocity in spherical polar coordinates.

The expression for acceleration in spherical polar coordinates is

$$\begin{aligned}\mathbf{a} &= (\ddot{r} - r\dot{\theta}^2 - r \sin^2 \theta \dot{\phi}^2) \mathbf{e}_r + \left[ \frac{1}{r} \frac{d}{dt} (r^2 \dot{\theta}) - r \sin \theta \cos \theta \dot{\phi}^2 \right] \mathbf{e}_\theta \\ &\quad + \frac{1}{r \sin \theta} \frac{d}{dt} (r^2 \sin^2 \theta \dot{\phi}) \mathbf{e}_\phi\end{aligned}$$

### Answer

(a)

$$\begin{aligned}\mathbf{r} &= r\mathbf{e}_r + z\mathbf{e}_z \\ \mathbf{v} = \dot{\mathbf{r}} &= \dot{r}\mathbf{e}_r + r\dot{\mathbf{e}}_r + \dot{z}\mathbf{e}_z + z\dot{\mathbf{e}}_z \\ \text{Now } \dot{\mathbf{e}}_z &= 0 \text{ as in a fixed direction} \\ \mathbf{e}_r &= \mathbf{i} \cos \theta + \mathbf{j} \sin \theta \\ \dot{\mathbf{e}}_r &= \dot{\theta}(-\sin \theta \mathbf{i} + \cos \theta \mathbf{j}) = \dot{\theta}\mathbf{e}_\theta \\ \text{So } \mathbf{v} &= \dot{r}\mathbf{e}_r + r\dot{\theta}\mathbf{e}_\theta + \dot{z}\mathbf{e}_z \\ \mathbf{a} = \dot{\mathbf{v}} &= \ddot{r}\mathbf{e}_r + \dot{r}\dot{\mathbf{e}}_r + (r\ddot{\theta})\mathbf{e}_\theta + r\dot{\theta}\dot{\mathbf{e}}_\theta + \ddot{z}\mathbf{e}_z \\ \text{Now } \dot{\mathbf{e}}_\theta &= \frac{d}{dt}(-\sin \theta \mathbf{i} + \cos \theta \mathbf{j}) = -\dot{\theta}\mathbf{e}_r \\ \text{So } \mathbf{a} &= \ddot{r}\mathbf{e}_r + \dot{r}\dot{\theta}\mathbf{e}_\theta + (r\ddot{\theta})\mathbf{e}_\theta - r\dot{\theta}^2\mathbf{e}_r + \ddot{z}\mathbf{e}_z \\ \Rightarrow \mathbf{a} &= (\ddot{r} - r\dot{\theta}^2)\mathbf{e}_r + (r\ddot{\theta} + 2r\dot{\theta})\mathbf{e}_\theta + \ddot{z}\mathbf{e}_z\end{aligned}$$

(b)

$$\begin{aligned}\mathbf{r} &= r\mathbf{e}_r \quad \mathbf{v} = \dot{r}\mathbf{e}_r + r\dot{\mathbf{e}}_r \\ \text{Now } \mathbf{e}_r &= \mathbf{i} \sin \theta \cos \phi + \mathbf{j} \sin \theta \sin \phi + \mathbf{k} \cos \theta \\ \dot{\mathbf{e}}_r &= \dot{\theta}(\mathbf{i} \cos \theta \cos \phi + \mathbf{j} \cos \theta \sin \phi - \mathbf{k} \sin \theta) \\ &\quad + \dot{\phi}(-\mathbf{i} \sin \theta \sin \phi + \mathbf{j} \sin \theta \cos \phi) \\ &= \dot{\theta}\mathbf{e}_\theta + \dot{\phi} \sin \theta \mathbf{e}_\phi \\ \text{So } \mathbf{v} &= \dot{r}\mathbf{e}_r + r\dot{\theta}\mathbf{e}_\theta + r\dot{\phi} \sin \theta \mathbf{e}_\phi\end{aligned}$$